

BEER GAME ORDER POLICY OPTIMIZATION USING GENETIC ALGORITHMS

*Jordi Bosch Pagans, Fernanda Strozzi, José-Manuel Zaldívar Comenges**

Contents

1. Introduction
 2. The Beer Game
 - 2.1. The simulation model
 - 2.2. The ordering policy
 - 2.3. The fitness function
 3. Genetic algorithms
 4. Beer game parameters estimation with GA
 5. Results
 6. Conclusions
- References

1. Introduction

The Beer Distribution Game (“Beer Game”), developed at the Sloan School of Management in early 1960’s (Jarmain, 1963), is a classic supply chain problem widely used in graduate business programs to teach the concepts of supply chain management (Mosekilde *et al.*, 1991).

The goal of the participant in the game is to minimise the costs of maintaining sufficient inventories of beer while at the same time avoiding out-of-stock condition that could lead to loss of customers. The Beer Game is notable for its ability to confuse typical human players (Serman, 1988, 1989) giving rise to instabilities in the supply chain as well as demand distortion (Chen *et al.*, 2000). The game is also used to illustrate how different decision policies influence the dynamics of a distribution system.

* European Commission, Joint Research Centre, Institute for Environment and Sustainability, T 272, 21020-Ispra (VA), Italy

Sterman (1989) formulated a four parameter discrete model for the order policy, based on the theory of bounded rationality (Davis *et al.*, 1986; Einhorn & Hogarth, 1985) and showed that this model captures the main aspects of the decisions taken in the game by real players.

Mosekilde and Larsen (1988) were first to show that a time-continuous version of the Beer Game model could produce deterministic chaos and other forms of complex behaviour (Zhanybay *et al.*, 2003).

In this work we are going to analyse the optimal order policies, i.e. the optimal parameters of the Sterman model, when a step-change occurs in the customer demand. The optimal policy considered is the policy that gives the minimum cost, accounting both for the costs to maintain a stock of goods and for the costs of having a backlog when it is not possible to satisfy the demand. Two scenarios have been analysed: all sectors apply the same order policies, or different policies are applied from sector to sector. The search of the optimal solution has been performed using Genetic Algorithms (Holland, 1975) due to the complexity of the objective cost function, which has many local minima and, in the case of different policies, many parameters.

The application of GAs optimisation techniques is a novelty in the case of Beer Game model but they have been applied in several managerial problems such as portfolio optimisation and job scheduling (Yen-Zen Wang, 2003).

Better performances are obtained when sectors apply different order policies compared with the same order policy. This is not surprising since when the participant applies different order policies there are eight parameters to optimise compared with two parameters when the same order policies are applied. Furthermore, when participants apply the same order policy, the optimal policy found using GAs is different from the analytical values obtained by Mosekilde *et al.* (1991). The differences will be discussed in the paper.

2. The Beer Game

The Beer Game is a realisation of a production-distribution system on four levels: Factory, Distributor, Wholesaler and Retailer, see fig. 1. The orders starting from the customer go to the Retailer, then to the Wholesaler, the Distributor, and finally reach the Factory. In the mean time, previous orders are moving from the Factory down through the supply chain until they reach the customer. This is a typical game for students that have to manage their stocks in order to cope with the variation of the customer demand, and at the same time trying to avoid out-of-stock conditions. The game is widely used in management schools as a means to convey to students the causal relationships between their decision-making and the behaviour of supply chains. The

typical results of the game are counterintuitive, because large oscillations appear in the order rate based on small increase in the customer demand (Sterman, 1988).

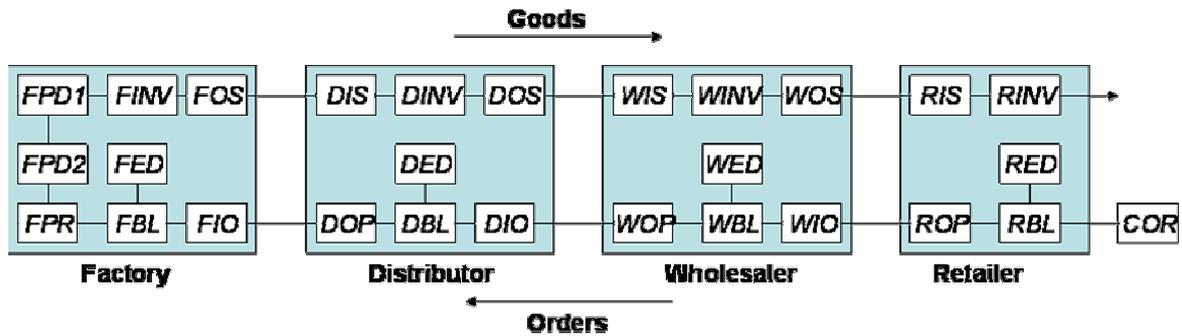


Figure 1. Basic structure of production-distribution system with state variables and orders flow (left arrow) and goods flow (right arrow) in the Beer game model.

In order to simplify this production-distribution system, several rules were defined (Jarman, 1963):

- there is only one inventory at each level initialised with 12 cases of beer;
- the time delay from passing of orders and shipments from one stage to the next is fixed to one week (one time period of the game);
- the production time is taken to be three weeks, and it is assumed that the production capacity of the brewery can be adjusted without limits;
- each week customers order beer from the retailer, who supplies the requested quantity out of his inventory.

A further typical simplification is that customer demand is four cases of beer per week until week 4 and steps to eight cases of beer per week at week five. In this paper we have analysed a set of customer demands that changes, at week five, from four to fifteen cases and then we have forced the system with a higher demand, i.e. forty cases, to test if the limit values found are maintained.

The objective for the participants (stock managers) in the game is to minimise cumulative sector costs at the end of the game. Considering the costs associated with inventory holding (€0.50 per case per week), stocks should be kept as small as possible. On the other hand, failure to deliver on request may force customers to seek alternative suppliers. For this reason, there are also costs associated with having backlogs of unfilled orders (€2.00 per case per week).

Stock managers, in all the sectors, have to decide, at the beginning of each week, the amount of beer to be ordered from the immediate supplier.

2.1 The Simulation Model

The simulation model consists of a high-dimensional iterated map that provides the sequence of operations that each sector should perform. The boxes in Fig 1 represent the state variables. Each variable has an initial letter that indicates the respective sector; thus *R* stands for retailer, *W* for wholesaler, *D* for distributor and *F* for factory. For example, in the wholesale sector, *WINV* is the inventory of beer, *WBL* the backlog of orders, *WIS* and *WOS* represent incoming and out going shipments, respectively, where *WIO* is the incoming orders, *WED* is the expected demand and *WO*

the orders placed by the wholesaler. One time step later, *WO*

becomes incoming orders to the distributor, *DIO*. The same notation is employed in the other sectors with the exception of the factory where there is a production rate, *FPR*, instead of placed orders and *FPD1* and *FPD2* represent the production delays. The exogenous customer order rate is given by *COR*.

The difference equations of the model (Thomsen *et al.*, 1992) that represent the operations conducted in each sector may be written for the wholesaler sector as example:

$$WINV_t = \begin{cases} WINV_{t-1} + WIS_{t-1} - WBL_{t-1} - WIO_{t-1} & \text{if } WINV_{t-1} + WIS_{t-1} \geq WBL_{t-1} + WIO_{t-1} \\ 0 & \text{otherwise} \end{cases} \quad (1)$$

Similar expressions hold for *RINV*, *DINV* and *FINV*.

$$WIS_t = DOS_{t-1} \quad (2)$$

again similar expressions are used for *RIS*, *DIS* and *FPD2*.

$$WBL_t = \begin{cases} WBL_{t-1} + WIO_{t-1} - WINV_{t-1} - WIS_{t-1} & \text{if } WBL_{t-1} + WIO_{t-1} \geq WINV_{t-1} + WIS_{t-1} \\ 0 & \text{otherwise} \end{cases} \quad (3)$$

Similar expressions are used for *RBL*, *DBL* and *FBL*.

$$WIO_t = ROP_{t-1} \quad (4)$$

with similar expressions for *DIO*, *FIO* and *FPD1*.

$$WOS_t = \text{MIN}\{WINV_{t-1} + WIS_{t-1}, WBL_{t-1} + WIO_{t-1}\} \quad (5)$$

with similar expressions for *DOS*, *FOS* and shipments out of retailer's inventory.

2.2. The ordering policy

Consistent with the theory of bounded rationality, Sterman (1989) has proposed (assuming the a stock manager applies adaptive expectations) that the expected demand may be expressed as follows:

$$WED_t = \theta \cdot WIO_{t-1} + (1 - \theta) \cdot WED_{t-1} \quad (6)$$

WED_t and WED_{t-1} are the expected demand at times t and $t-1$, respectively, WIO is the incoming orders, and $\theta(0 \leq \theta \leq 1)$ is a parameter that controls the rate at which expectations are updated. $\theta = 0$ corresponds to stationary expectations, and $\theta = 1$ describes a situation in which the immediately preceding value of received orders is used as an estimate of future demand. Statistical analysis show that θ is typically 0.25 (Mosekilde *et al.*, 1991).

The order placed are determined in accordance with the expression

$$WOP_t = \max\{0, WOP_t^*\}$$

$$\text{where } WOP_t^* = WED_t + WAS_t + WASL_t \quad (7)$$

i.e. the order decision has to be positive and it is a sum of the number of cases that the manager expected to be ordered (WED_t : Wholesaler Expected Demand), the number of cases necessary to fill the inventory until a desired level (WAS_t : Wholesaler Stock Adjustment) and the number of cases to maintain the supply chain up to a certain value ($WASL_t$: Wholesaler Adjustment of Supply Line). The former quantities are respectively defined as follows:

$$WAS_t = \alpha_s (DINV - WINV_t + WBL_t) \quad (8)$$

where $WDINV$ and $WINV_t$ denote desired and actual inventories, respectively, and WBL_t is the backlog of orders. The stock adjustment parameter α_s is the fraction of the discrepancy between desired and actual inventory ordered in each round. $WDINV$ is constant and equal to 14 cases of beer.

A statistical study with a significant number of participants (Thomsen *et al.*, 1992) showed that the stock adjustment parameters α_s varies between 0 and 1.

In analogy with the stock adjustments, the supply chain adjustments are expressed as:

$$WASL_t = \alpha_{SL} (DSL - WSL_t) \quad (9)$$

$$WSL_t = WIS_t + DIO_t + DBL_t + DOS_t$$

where DSL and WSL_t denote the desired and actually supply chain of the wholesaler, respectively. α_{SL} is the fractional adjustment rate, i.e., the fraction of the discrepancy between desired and actual supply line ordered in each round.

Defining $\beta = \alpha_{SL} / \alpha_s$ and $Q = DINV + \beta \cdot DSL$, the expression for the indicated order rate becomes

$$WOP_t^* = WED_t + \alpha_s (Q - WINV_t + WBL_t - \beta \cdot WSL_t) \quad (10)$$

$DINV$, DSL , and β are all non-negative, implying that $Q \geq 0$. (Thomsen *et al.*, 1992) consider the case in which $DINV$, DBL , α_S , β were the same for the participants.

As the supply line does not directly influence costs, nor is it as salient (important) as the inventory, then, $\alpha_{SL} \leq \alpha_S$ and $\beta \leq 1$. β may be interpreted as the fraction of the supply line taken into account by the participants.

A couple of values of the parameters (α_S, β) correspond to a specific behaviour of the participants: high α_S means high attention to the inventory, high β means high attention to the supply chain in comparison with the inventory.

2.3. The fitness function.

In this work, the main goal of each participant will be to minimise the global score i.e. the cost of the chain. This results in the minimisation of the following objective function

$$J = \sum_{i=1}^n (2 * (RBL_i + WBL_i + DBL_i + FBL_i) + 0.5 * (RINV_i + WINV_i + DINV_i + FINV_i)) \quad (11)$$

where n is the total number of weeks, 60. Furthermore, in accordance with Mosekilde *et al.* (1991), we restricted the search space into α_S and β considering $Q = 17$ and $\theta = 0.25$, respectively.

Finally, it was decided to determine the optimal parameters for the ordering policy for two different situations. In the first case all sectors were assumed to apply the same parameter values (α_S and β), whereas in the second case, all four sectors had different parameters. Figures 2 and 3 show the effective inventory (inventory-backlog) and order rate evolutions of the four sectors over 60 weeks simulations for both scenarios using the optimal parameters founded with GAs techniques.

In both cases, the effective inventories initially decrease and afterwards give rise to a set of oscillations that increase from retailer to factory. This behaviour is a result of the change of the customer order rate at week 5 from 4 to 8 cases of beer. This fact produces an increase of the orders placed by the retailer that is propagated in a wavelike manner through the supply chain to the factory, depleting the inventories one by one and producing a successive increase of the order rates to fill the generated backlogs. Once the backlogs are eliminated, the inventories show a strong increase because of the high order rates. This is especially noticeable for sectors close to factory. Finally, the inventories are again reduced through adjustments of the order rates. Despite the analogous response in both scenarios, it is noticeable that in the second scenario, when the four sectors have different order policies, the supply chain presents lower

and smoother oscillations. In particular, the distributor effective inventory in the first scenario reaches one hundred cases of beer, while in the second scenario the biggest effective inventory is slightly greater than twenty units.

3. Genetic Algorithms

Genetic Algorithms (GAs) are optimisation algorithms based on the natural selection rule from the evolutionary theories of Darwin, i.e. the survival of the fittest individuals to the environment. Building on the idea, Holland (1975) developed the first GAs where an optimisation problem is turned into an evolutionary process, in which a group of individuals evolve to adapt better to a fitness function generation after generation.

Since then, GAs have been applied on many fields, the technique showing itself to be robust powerful optimisation tool especially suited for problems with large search spaces, and with complex or non-analytic objective functions (<http://cs.felk.cvut.cz/~xobitko/ga/>)

GAs generate randomly, or based on background knowledge, an initial set of possible solutions called a population. Each potential solution is encoded into a string called the chromosome. Depending on the type of problem, chromosomes may be built-up of characters, bits, integer or real numbers. Subsequently, the fitness of each chromosome is evaluated using a pre-specified objective function. A new offspring population is generated from the actual population by using three operators: selection, crossover and mutation. The first operator selects pairs of chromosomes called parents from the actual population in order to create a mating pool for the offspring generation. This is a stochastic process where the probability of each individual is proportional to its relative fitness within the current population. The crossover operator generates two offspring chromosomes of the new population starting from two of the old one by redistributing the information from the parent's string. After that, the mutation operator introduces an alteration on a randomly selected point of the string. Finally, the new population replaces the actual population, or a set of chromosomes of the actual population. The algorithm repeats the new population generation process until one of the end conditions, such as number of generations or the error improvement, is satisfied.

The crossover and mutation operators are stochastic processes with defined probabilities. The crossover probability, or crossover rate, is generally high, about 80-95%, to ensure an evolution process. By contrast, the mutation probability is often very low, generally less than 1%. This is because high mutation rates make genetic algorithms act as random search algorithms. On the other hand, the small contribution from mutations plays the important role of

driving the evolution into new areas of the search space to avoid falling into local minima (<http://www.rennard.org/alife/english/gavintrgb.html>).

4. Beer Game parameters estimation with GA

In this work, GAs were used as optimisation techniques on the beer game order policy model. The election of GAs to solve this problem was based on the fact that the function J that we want to minimise has many local minima and it is not differentiable. The minimisation tools gradient based need differentiability and the ones that do not need differentiability, such as the Nelder-Mead simplex method (Lagarias *et al.*, 1998), can be very slow with 8 parameters.

Once the problem is defined, the following steps for a GA implementation are definition of the fitness function and the chromosome structure. In both cases, the selected fitness function is the overall weekly score of the four sectors that in our case is the function J defined by Eq (11).

The chromosome structure in the first case contains two genes, one for α_S and one for β . It was also decided to encode chromosomes in bits. As the parameters values are contained between 0 and 1 and it was decided to use three decimal digits, each gene resulted in 10 bits, and therefore a 20 bits chromosome structure. A diagram of the chromosome structure is displayed in Figure 4. Analogously, in the second case the chromosome structure contains eight genes. This is one α_S and one β for each of the four sectors. As in the previous case, genes were encoded in 10 bits strings resulting in 80 bits chromosome.

Once the fitness function and the chromosome structures were defined, a GA was implemented on Matlab with the genetic operators, selection, crossover and mutation, described previously. In particular, the crossover operator implemented uses either one or two crossover points and parents selection is carried out using the method of rank selection.

5. Results

Several runs of the implemented GAs were carried out for the two studied scenarios. All runs of GAs were carried out with a population size of 30, a crossover rate of 90% and a mutation rate of 1%. The maximum number of iterations was 200 when all sectors applied equal ordering policy, and 500 when the four involved sectors applied different policies.

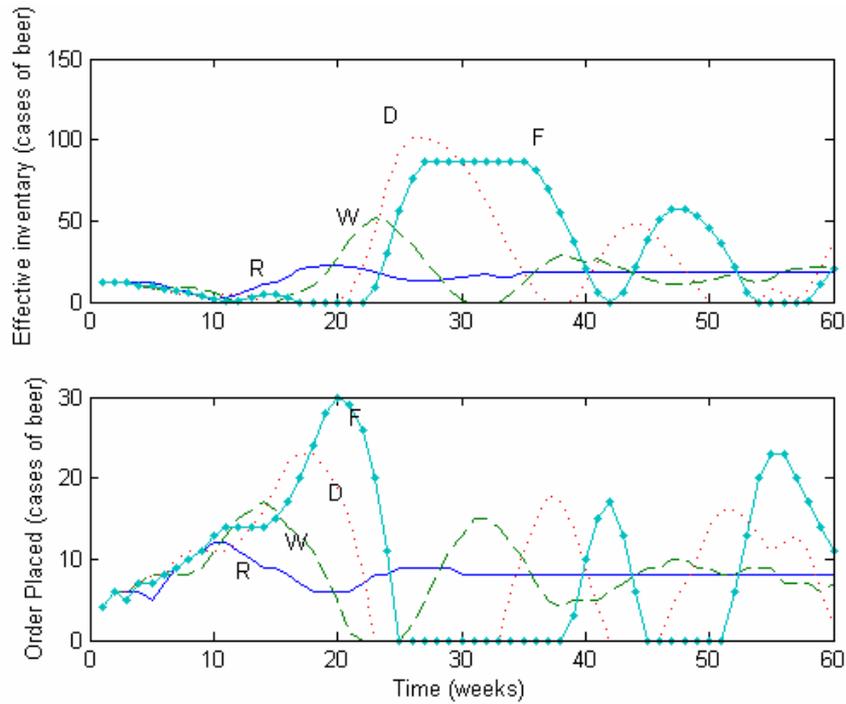


Figure 2. Effective inventory i.e. the number of cases in the stock (upper layer) and order placed (lower layer) of retailer (continuous line), wholesaler (dashed line), distributor (dotted line) and factory (continuous pointed line). Same order policy. Customer demand changes from 4 to 8 cases of beer per week in the fifth week. $\theta=0.250$, $Q=17$, optimal parameters: $\alpha_s=0.317$ and $\beta=0.016$.

Figures 2 and 3 show the effective inventory (inventory-backlog) and order rate evolutions of the four sectors over 60 weeks simulations using the optimal order parameters obtained with GA considering the four sectors having same and different ordering policies, respectively. In both cases, the effective inventories initially decrease and afterwards present a set of oscillations that increase from retailer to factory. This behaviour is a result of the change of the customer order rate at week 5 from 4 to 8 cases of beer. This fact produces an increase of the orders placed by the retailer that propagates wavelike through the supply chain in the direction of the factory producing the inventories depletion and the successive increase of the order rates to fulfil the generated backlogs. Once the backlogs are satisfied, the inventories increase because of the increase in the order rates, especially noticeable on sectors close to factory.

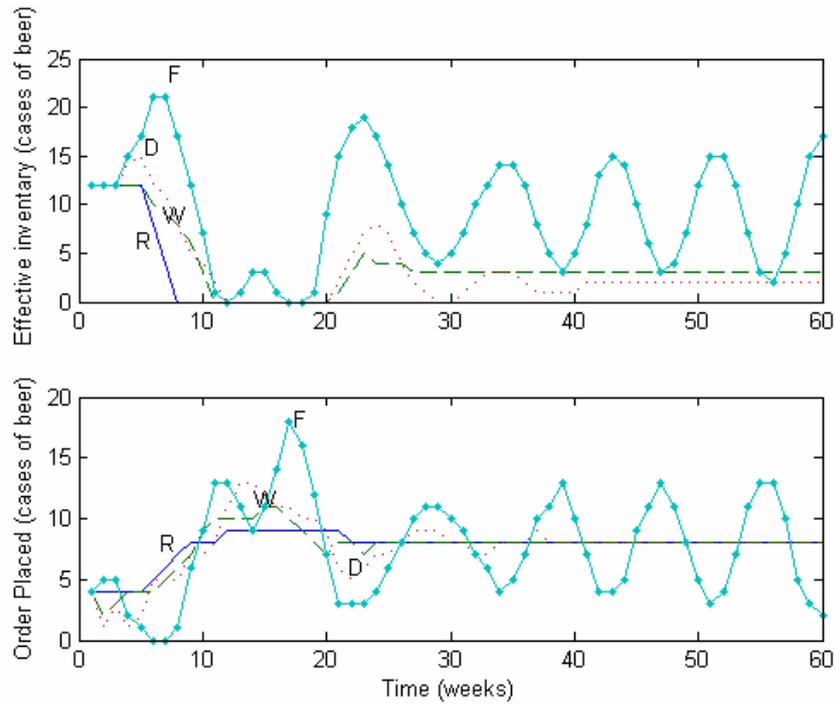


Figure 3. Effective inventory (upper panel) and order placed (lower panel) evolutions of Retailer (continuous line), Wholesaler (dashed line), Distributor (dotted line) and Factory (continuous pointed line) with different order policies. $\theta = 0.250$, $Q = 17$, optimal parameters: $\alpha_R = 0.09400$, $\beta_R = 0.2570$, $\alpha_W = 0.9790$, $\beta_W = 0.5910$, $\alpha_D = 0.9910$, $\beta_D = 0.6320$, $\alpha_F = 0.9600$ and $\beta_F = 0.2470$. Customer demand changes from 4 to 8 cases.

Mosekilde et. al, (1991) shown analytically that the fitness function J has a global minimum, when $\beta=0.6$. The discrepancy with our results using GAs ($\beta=0.016$) can be due to the flatness of surface J near $\beta=0.6$ that implies that GAs algorithm is very slow and stops before the analytical minimum because some tolerances are reached. Anyway it is well known that GAs do not always finds the best solution, but a “enough good” solution in the sense that the fitness function assumes one of its lowest local minima. Another aspect of GAs to observe is that they give no information about the stability of the minimum. In the case in which the participants apply the same policy, the minimum founded is surrounded by many others minima and than a small change in the policy can give rise to very different score. The analytical solution is placed in stable.

When the four sectors have different order policies the inventory of the participants presents lower and smoother oscillations and in particular distributor effective inventory is always beyond twenty units.

In the first scenario the fitness function i.e. the final score is €2972.5, whereas in the second scenario is €1056. In the first scenario the retailer is the sector with the lowest score, €434, while wholesaler, distributor and factory have a score of €499, €884.5 and €155, respectively. On the other hand, in the second scenario, the sector with the lowest score is the distributor, €194, and the other sectors present scores not very different. This is because all sectors

accomplish to contain their effective inventories when the customer order rate increases. That is to say, there is not a clear winner as in the first scenario, but all sectors reach the objective to keep low inventories and to avoid backlogs.

Figures 4 and 5 show the best solutions obtained from ten runs for the four sectors operating the same and different orders policies, respectively. In the first case, solutions are homogeneously distributed on two close zones both with small values of α_S and β . The best order policy i.e. the one with the minimum score, corresponds to $\alpha_S=0.324$ and $\beta=0.021$.

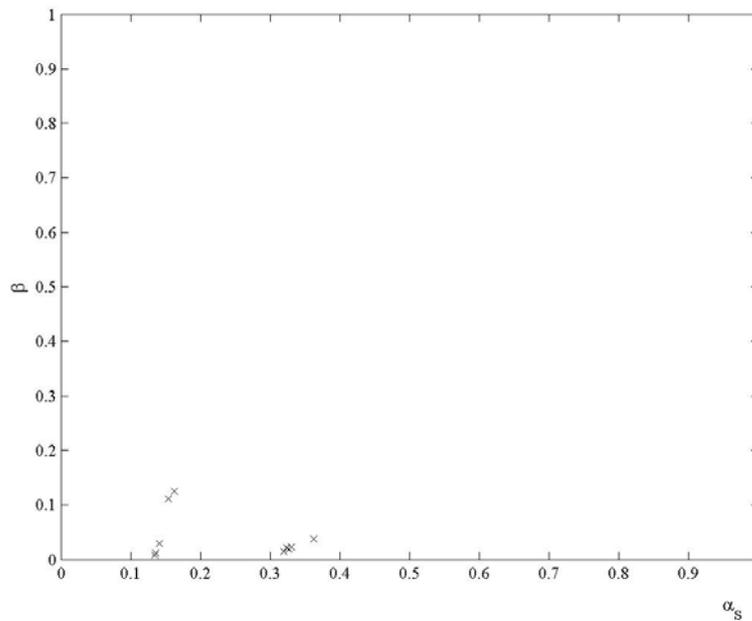


Figure 4. Solutions (crosses) obtained from ten runs of GA algorithm after 200 generations considering one order policy in the $\alpha_S - \beta$ space.

In the second scenario, solutions appear to be placed on certain regions of the parameter space depending on the involved sector, moreover they are wider distributed as the involved sector is farther from the factory on the supply chain. Retailer best solutions are located on low values of α_S (smaller than 0.2) it means that retailer has to adjust the stock slowly. On the contrary, the suggestion for the wholesaler is to have α_S bigger than 0.2 than it has to be quicker than retailer in adjusting the stock and β values concentrated near 0.6. Distributor and Factory have to be both very quick in adjusting inventory (α_S near one) but Factory has to be slower than Distributor in adjusting the supply chain.

The optimal β values increase as sectors are farther from the Factory, i.e. the production source, as it can be seen in Figure 5 for the Factory, Distributor and Wholesaler. This fact is not observed for the retailer sector because of the definition of β and those retailer solutions present low α_S values. As previously stated, β is the relation between the supply line and the stock

fractional adjustment rates, α_{SL} and α_S , and is contained between 0 and 1 since it is unlikely that participants place more emphasis on the supply line than in the stock. Consequently, at low values of α_S , β becomes not significant and thus the best solutions are spread over a large range.

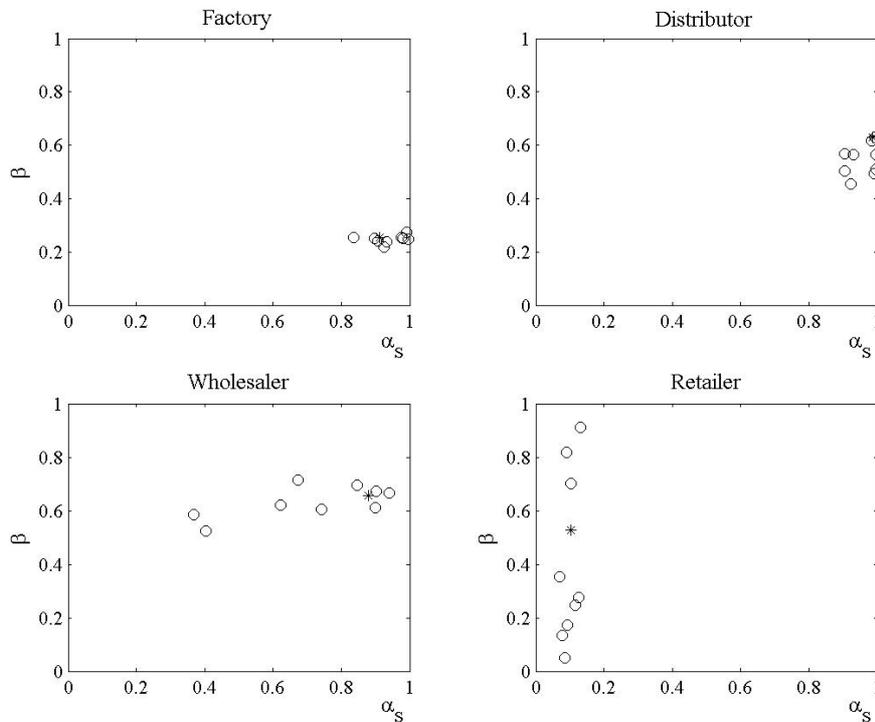


Figure 5. Solutions (best, asterisk; others, circles) obtained from ten runs of GA algorithm after 500 generations considering different order policies in the corresponding $\alpha_S - \beta$ spaces.

In order to check of the solutions given by the GAs algorithm, the fitness function, J , was represented when all sectors apply equal ordering policy. The contour plot of J was calculated on the entire search space with a 0.005 resolution, and on the area where best solutions were obtained with a 0.001 resolution which is the same used by the GA (see Figures 6 and 8). Because of the large range of the values, figure 6 displays results as the logarithm of J . As can be seen in figure 6, J presents two main zones of minima located at low values of α_S and β and several regions of minima widely spread on α_S . More detailed views of these two zones are given in figures 8 and 9. Which represent the surface and a contour plot of J in a smaller region respectively, together with the achieved solutions with GA. It is also noticeable the high number of local minima present on J that makes this optimisation problem not feasible to standard optimisation algorithms.

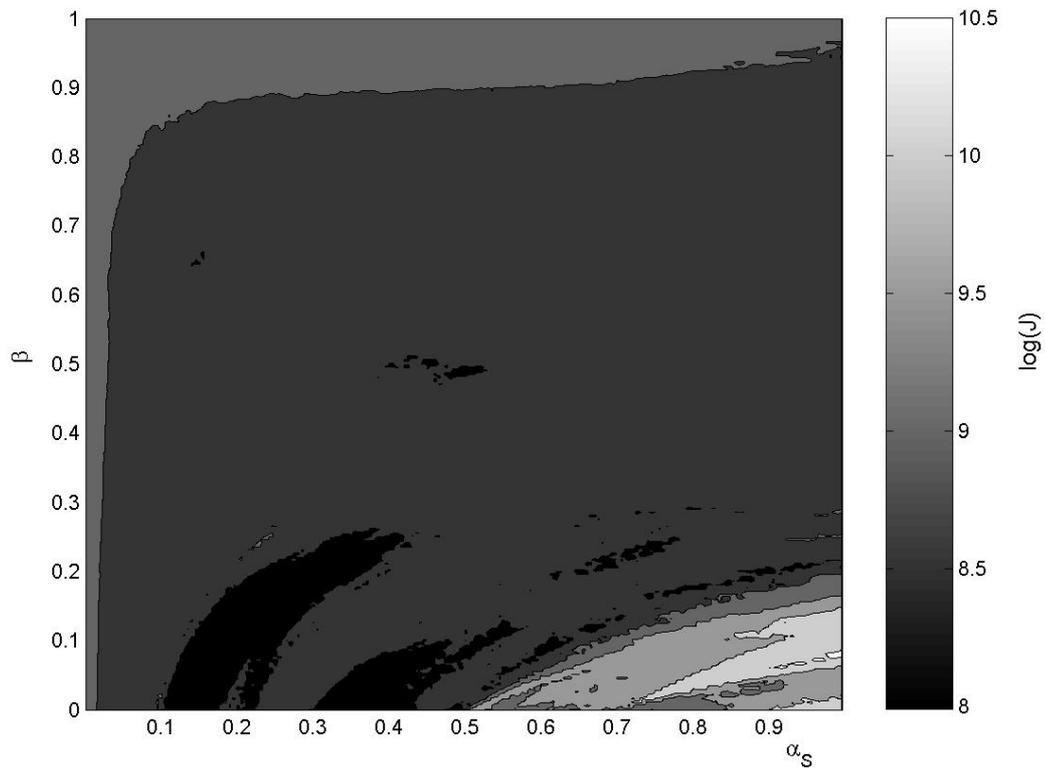


Figure 6. Contour plot of $\log(J)$ considering one ordering policy in the $\alpha_S - \beta$ space.

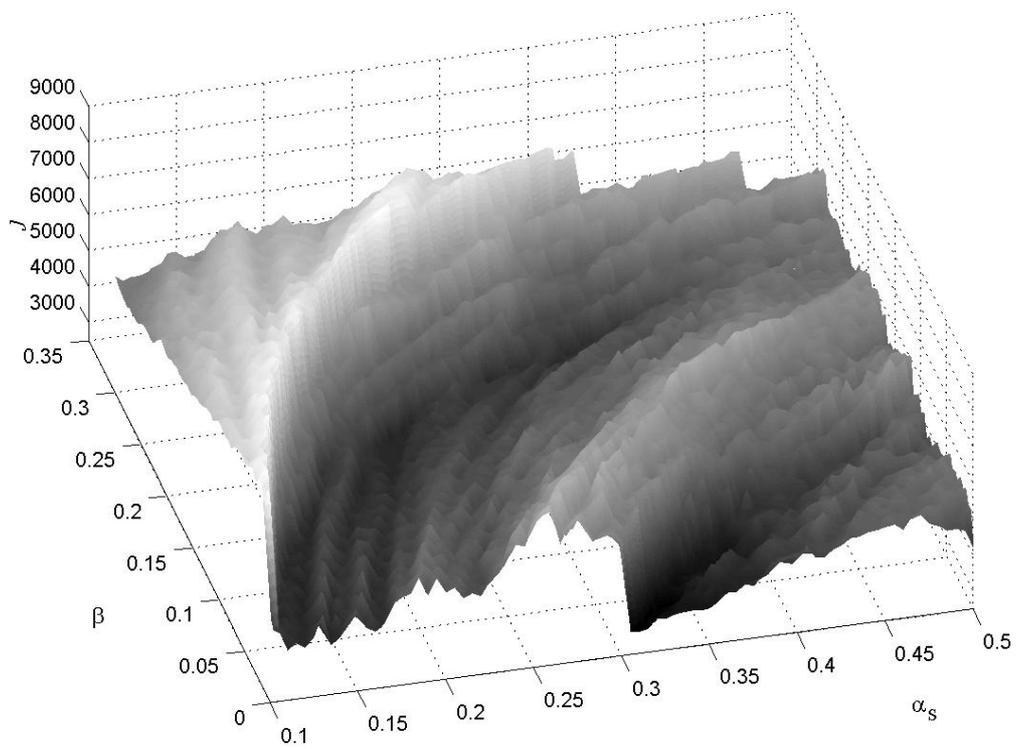


Figure 7. Surface plot of J of the area containing the lower values in the $\alpha_S - \beta$ space.

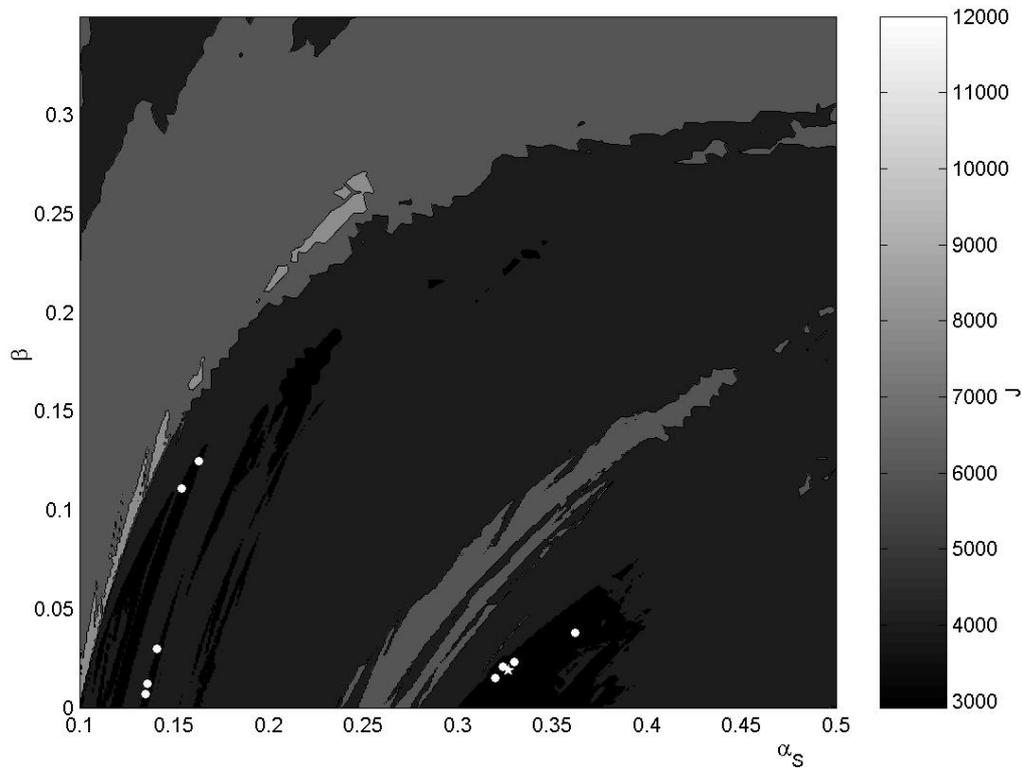


Figure 8. Contour plot of J considering one ordering policy in the $\alpha_S - \beta$ space and obtained solutions with GA (white circles and white star for best one).

6. Conclusions

In the present study, the optimal parameters for the order policy of the beer game for 60 weeks simulations have been obtained using GA in two different scenarios. These scenarios consider the sectors having identical and different order policies. The search of the optimal solution has been performed using Genetic Algorithms (Holland, 1975) due to the complexity of the objective cost function, which has many local minima and, in the case of different policies, many parameters.

Results have shown that best performance is obtained when sectors have different order policies rather than having the same. Furthermore, the first case leads to a situation where only one sector reaches the objective to have minimal inventory fluctuations and backlogs, while in the second scenario all sectors reach this objective. The results is not surprising because in the second case we have more parameters and than more possibilities to find good solutions.

In the first case, the optimal order policy was found on low values of α_S and extremely low of β . This combination of parameters results in a slow stock adjustment policy with carelessness of placed orders. Despite the fact that these parameters were found to be the optimal in the

search space, the chain still presents large oscillations on the effective inventories due to the customer order rate increase. Anyway this solution does not correspond to the analytical one founded by Mosekilde et al. (1991) which find the optimum near $\beta=0.6$. The discrepancy with our results using GAs ($\beta=0.016$) can be due to the flatness of surface J near $\beta=0.6$ that implies that GAs algorithm is very slow and stops before the analytical minimum since some tolerances are reached. In any case, it is well known that GAs do not always finds the best solution, but a “enough good” solution in the sense that the fitness function assumes one of its lowest local minima.

Having different order policies leads to an optimal solution that faces the order rate increase of the customer keeping the inventories within desired bounds without large fluctuations and with minimal backlogs. This is achieved by three factors that may be summarised as:

- A retailer sector with low values of α_S that responds to the customer order rate increase with still adjustments. This fact avoids the propagation of the customer order rate increase wavelike through the chain as observed in the other scenario.
- A factory sector with high values of α_S that permits to deliver constantly without delays due to depletion of its inventory.
- An increasing importance of the orders placed as involved sectors are farther from the factory that avoids over-ordering, and thus the amplification of order rate increase through the chain.

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